Comparison of Gauss Jacobi Method and Gauss Seidel Method using Scilab

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ABSTRACT

Numerical Method is the important aspects in solving real world problems that are related to Mathematics, science, medicine, business etc. In this paper, We comparing the two methods by using the scilab 6.0.2 software coding to solve the iteration problem. which are Gauss Jacobi and Gauss Seidel methods of linear equations.

KEYWORDS: Linear equation, Gauss Jacobi Method, and Gauss Seidel Method

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INTRODUCTION

A Linear System of variables x_1, x_2, \dots, x_n is linear equations of the form $a_1x_1+a_2x_2+\dots, a_nx_n=b_n$. The value of a_1, a_2, \dots, a_n are any constant real/complex numbers. The constant a_1 is called the coefficient of x_1 and b is called the constant term of the equation. A system of linear equations (or linear system) is a finite collection of linear equation in same variables.

$$a_{11}x_1 + a_{12}x_2 + \dots a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \dots a_{2n}x_n = b_2$$

.....

$$a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nn}x_n = b_n$$

A solution of a linear system is n- tuple (v_1, v_2, \dots, v_n) of numbers that satisfied each linear equation when the values v_1, v_2, \dots, v_n are substituted for x_1, x_2, \dots, x_n respectively.

There are two Iterative methods for the solving simultaneous equations.

1. Gauss Jacobi Method

2. Gauss Seidel Method

It can be shown that the Gauss-Seidel method converges twice as fast as Jacobi method.

1. Gauss Jacobi Method

METHODS

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Let us explain this method is the case of linear equations in three unknowns.

Consider the system of linear equations,

$$a_1x+b_1y+c_1z = d_1$$

 $a_2x+b_2y+c_2z = d_2$
 $a_3x+b_3y+c_3z = d_3$

or converges
$$|a_1| > |b_1| + |c_1|$$

 $|b_2| > |a_2| + |c_2|$
 $|c_3| > |a_3| + |b_3|$

For iterative process

$$x = \frac{1}{a_1} (d_1 - b_1 y - c_1 z)$$

$$y = \frac{1}{b_2} (d_2 - a_2 x - c_2 z)$$

$$z = \frac{1}{c_2} (d_3 - a_3 x - b_3 z)$$

If $x^{(0)}, y^{(0)}, z^{(0)}$ are the initial values of x,y,z respectively, then

 $x^{(1)} = \frac{1}{a_1} (d_1 - b_1 y^{(0)} - c_1 z^{(0)})$ $y^{(1)} = \frac{1}{b_2} (d_2 - a_2 x^{(0)} - c_2 z^{(0)})$ $z^{(1)} = \frac{1}{c_3} (d_3 - a_3 x^{(0)} - b_3 z^{(0)})$ International Journal of Trend in Scientific Research and Development (IJTSRD) @ www.ijtsrd.com eISSN: 2456-6470

Again using these value $x^{(1)}, y^{(1)}, z^{(1)}$ we get

$$x^{(2)} = \frac{1}{a_1} (d_1 - b_1 y^{(1)} - c_1 z^{(1)})$$

$$y^{(2)} = \frac{1}{b_2} (d_2 - a_2 x^{(1)} - c_2 z^{(1)})$$

$$z^{(2)} = \frac{1}{c_3} (d_3 - a_3 x^{(1)} - b_3 z^{(1)})$$

Proceeding in the same way, if the rth iterates are $x^{(r)}, y^{(r)}, z^{(r)}$, the iteration scheme reduces to

$$x^{(r+1)} = \frac{1}{a_1} (d_1 \cdot b_1 y^{(r)} \cdot c_1 z^{(r)})$$

$$y^{(r+1)} = \frac{1}{b_2} (d_2 \cdot a_2 x^{(r)} \cdot c_2 z^{(r)})$$

$$z^{(r+1)} = \frac{1}{c_3} (d_3 \cdot a_3 x^{(r)} \cdot b_3 z^{(r)})$$

The procedure is continued till the convergence is assured (correct to required decimals).

PROBLEM: Solve the following equation by Gauss Jacobi Method.

10x-5y-2z=3; 4x-10y+3z=-3; x+6y+10z=-3.

Solution:

The below result is find out by the manual work:

n	X	У	Z	2
1	0.3	0.3	-0.3	c
2	0.39	0.33	-0.51	D
3	0.363	0.303	-0.537	
4	0.3441	0.2841	-0.5181	_
5	0.33843	0.2822 /	-0.50487	
6	0.340126	0.283911	-0.503163	
7	0.3413229	0.2851015	-0.5043592	aı
8	0.34167891	0.2852214	-0.50519319	no
9	0.341572062	0.2851136 <mark>07</mark>	-0.505300731	:Se

2. Gauss-Seidel Method

This is only a refinement of Gauss-Jacobi Method As before,

$$x = \frac{1}{a_1} (d_1 \cdot b_1 y \cdot c_1 z)$$

$$y = \frac{1}{b_2} (d_2 \cdot a_2 x \cdot c_2 z)$$

$$z = \frac{1}{c_3} (d_3 \cdot a_3 x \cdot b_3 y)$$

We start with the initial values $y^{(0)}$, $z^{(0)}$ for y and z and get $x^{(1)}$ That is,

$$x^{(1)} = \frac{1}{a_1} (d_1 - b_1 y^{(0)} - c_1 z^{(0)})$$

We use $z^{(0)}$ for z and $x^{(1)}$ for x instead of $x^{(0)}$ as in the Jacobi's Method, we get

$$y^{(1)} = \frac{1}{b_2} (d_2 - a_2 y^{(1)} - c_2 z^{(0)})$$

Now , having known $x^{(1)}$ and $y^{(1)}$ use $x^{(1)}$ for x and $y^{(1)}$ for y,we get 2

$$z^{(1)} = \frac{1}{c_3} (d_3 - a_3 x^{(1)} - b_3 y^1)$$

In finding the values of the unknowns, we use the latest available values on the right hand side. If $x^{(r)}, y^{(r)}, z^{(r)}$ are the rth iterates, then the iterates scheme will be (r+1) 1 (1) (r) (r)

$$x^{(r+1)} = \frac{1}{a_1} (a_1 - b_1 y^{(r)} - c_1 z^{(r)})$$

$$y^{(r+1)} = \frac{1}{b_2} (a_2 - a_2 x^{(r+1)} - c_2 z^{(r)})$$

$$z^{(r+1)} = \frac{1}{c_3} (a_3 - a_3 x^{(r+1)} - b_3 y^{(r+1)})$$

This Process of iteration is continued until the convergence is assured.

evelop PROBLEM: Solve the following equation by Gauss-Seidel Method.

Solution:

	Ν	х	У	Z
Z		0.3	0.42	-0.582
	2	0.3936	0.28284	-0.509064
	3	0.3396072	0.28312364	-0.503834928
	4	0.34079485	0.28516746	-0.50517996
	5	0.3415547	0.28506792	-0.505196229
	6	0.3414947	0.285039	-0.5051728
	7	0.3414849	0.28504212	-0.5051737

By using the Scilab coding the result is shown below:

-	finalgaussseidel.sci (C:\Users\Admin\Documents\finalgaussseidel.sci) - SciNotes
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<pre>ifinalgausseidel.sci (C\Users\Admin\Documents\finalgausseidel.sci) - SciNotes File Edit Format Options Window Execute ? File Edit Format Options File Edit Format Optio</pre>	
1	clc;clear; <u>close</u> ;
2	
3	x0=0;y0=0;z0=0;
4	<u>deff('x=fl(y,z)','x=(3+5*y+2*z)/10')</u>
5	<pre>deff('y=f2(x,z)','y=(-3-4*x-3*z)/-10')</pre>
6	<pre>deff('z=f3(x,y)','z=(-3-x-6*y)/10')</pre>
7	for i=1:7
8	x0=f1(y0,z0);
9	y0=f2(x0,z0);
10	z0=f3(x0,y0);
11	<pre> printf('\tx(%i)=%g\n\n\ty(%i)=%g\n\n\tz(%i)=%g\n\n\n\n',i,x0,i,y0,i,z0)</pre>
12	end
13	printf('thus.we.find.that.solution.converges.to.%g,%g.and.%g',x0,y0,z0)
14	

By using Scilab coding the result shown below:

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fina	allgaussjacobi.sci 🐹
1	clc;clear; <u>close</u> ;
2	
3	x0=0;y0=0;z0=0;
4	<pre>deff('x=f1(y,z)','x=(3+5*y+2*z)/10')</pre>
5	<pre>deff('y=f2(x,z)','y=(-3-4*x-3*z)/-10')</pre>
6	<pre>deff('z=f3(x,y)','z=(-3-x-6*y)/10')</pre>
7	for i=1:9
8	<pre>x1=f1(y0,z0);</pre>
9	····y1=f2(x0,z0);
10	<pre>z1=f3(x0,y0);</pre>
11	$\cdots \cdot printf(' \ tx(\i) = \cdot g \ n \ ty(\i) = \cdot g \ ty(\ ty(\i) = \cdot g \ ty(\ ty(\ ty(\ ty(\ ty(\ ty(\ ty(\ ty$

\tz(%i)=%g\n\n\n',i,x1,i,y1,i,z1) x0=x1;y0=y1;z0=z1; 12 13

rintf('Thus-we-find-that-solution-converges-to-%g,%g-and-%g',x0,y0,z0) 14 15

n	X	У	Z
1	0.3	0.3	-0.3
2	0.39	0.33	-0.51
3	0.363	0.303	-0.537
4	0.3441	0.2841	-0.5181
5	0.33843	0.28221	-0.50487
6	0.340131	0.283911	-0.503169
7	0.341322	0.285102	-0.50436
8	0.341679	0.285221	-0.505193
9	0.341572	0.285114	-0.5053

The Actual Values are x=0.3415, y=0.2852, and z=-0.5053.

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	Ν	х	У	Z	
	1	0.3	0.42	-0.582	
	2	0.3936	0.28284	-0.509064	
	3	0.33960	0.283124	-0.503835	
	4	0.340795	0.285167	-0.50518	
	5	0.341548	0.285065	-0.505194	
	6	0.341494	0.285039	-0.505173	
	7	0.341485	0.285042	-0.505174	
+	ual	value are r	-0241E -	-0.20E2 a	-

The Actual value are **x=0.3415**, **y=0.2852**, and **z= -0.5053**.

CONCLUSION

There are different methods of solving of linear equation some are direct methods while some are iterative methods. In this paper , two Iteration methods of solving of linear equation have been presented where the Gauss-Seidel Method proved to be the best and effective in the sense that it converge very fast with Scilab Software. REFERENCE

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